

**Differential Geometry I**  
**Exercise Sheet no. 12**

**Exercise 1** Let  $(M^n, g)$  be a Riemannian manifold and  $(U_\varphi, \varphi)$  be a chart on  $M$ .

- (a) Show that the components  $R^l_{ijk} := d\varphi^l \left( R \left( \frac{\partial}{\partial \varphi^i}, \frac{\partial}{\partial \varphi^j} \right) \frac{\partial}{\partial \varphi^k} \right)$  of the curvature tensor  $R$  of  $g$  on  $U_\varphi$  are given in terms of the Christoffel symbols associated to  $(U_\varphi, \varphi)$  by

$$R^l_{ijk} = \frac{\partial \Gamma^l_{kj}}{\partial \varphi^i} - \frac{\partial \Gamma^l_{ki}}{\partial \varphi^j} + \sum_{m=1}^n (\Gamma^l_{mi} \Gamma^m_{kj} - \Gamma^l_{mj} \Gamma^m_{ki}).$$

- (b) Deduce that, if  $\text{ric} = \sum_{i,j=1}^n \text{ric}_{ij} d\varphi^i \otimes d\varphi^j$  denotes the decomposition of the Ricci-tensor of  $g$ , then

$$\text{ric}_{ij} = \sum_{k=1}^n R^k_{kij} = \sum_{k=1}^n \left( \frac{\partial \Gamma^k_{ji}}{\partial \varphi^k} - \frac{\partial \Gamma^k_{jk}}{\partial \varphi^i} + \sum_{m=1}^n (\Gamma^k_{mk} \Gamma^m_{ji} - \Gamma^k_{mi} \Gamma^m_{jk}) \right).$$

**Exercise 2**

Let  $(M := M_1 \times M_2, g := g_1 \oplus g_2)$  be the product of two Riemannian manifolds as in Exercise 3.(b) of Sheet no. 10.

- (a) Show that the Levi-Civita connection  $\nabla$  of  $(M, g)$  is given by

$$\nabla_{(X_1, X_2)}(Y_1, Y_2) = \nabla_{X_1}^{M_1} Y_1 + \nabla_{X_2}^{M_2} Y_2 + \partial_{X_1} Y_2 + \partial_{X_2} Y_1,$$

for all  $X_1, Y_1 \in \Gamma(\pi_1^* T M_1)$ ,  $X_2, Y_2 \in \Gamma(\pi_2^* T M_2)$  and where  $\partial_{X_1} Y_2$  (resp.  $\partial_{X_2} Y_1$ ) denotes the usual derivative (make sense of this).

- (b) Deduce that the curvature tensor  $R$  of  $(M, g)$  is given by

$$R^M_{X,Y} Z = R^{M_1}_{X_1, Y_1} Z_1 + R^{M_2}_{X_2, Y_2} Z_2,$$

for all  $X_i, Y_i, Z_i \in T_{x_i} M_i$ ,  $i = 1, 2$ , where  $X := X_1 + X_2$ ,  $Y := Y_1 + Y_2$  and  $Z := Z_1 + Z_2$ . (Here we write  $R_{X,Y}$  instead of  $R(X, Y)$  as this is better for typesetting in this context.)

- (c) Calculate the Ricci tensor and the scalar curvature of  $M$  in terms of the Ricci tensor and the scalar curvature of  $M_1$  and  $M_2$ .

**Exercise 3**

Let  $E, F \rightarrow M$  be (real or complex) vector bundles with connections  $\nabla^E, \nabla^F$  over a given manifold  $M$  and  $x \in M$  be a point. Prove the following identities:

- (a) The curvature tensor of the connection  $\nabla^E \oplus \nabla^F$  on  $E \oplus F \rightarrow M$  is given by

$$R_{X,Y}^{E \oplus F} = R_{X,Y}^E \oplus R_{X,Y}^F,$$

for all  $X, Y \in T_x M$ .

- (b) The curvature tensor of the tensor connection on  $E \otimes F \rightarrow M$  as defined in Exercise 3 of Sheet no. 11 is given by

$$R_{X,Y}^{E \otimes F} = R_{X,Y}^E \otimes \text{Id}_F + \text{Id}_E \otimes R_{X,Y}^F,$$

for all  $X, Y \in T_x M$ .

- (c) The curvature tensor of the dual bundle  $E^* \rightarrow M$  endowed with the induced connection is given by

$$(R_{X,Y}^{E^*} \alpha)(V) = -\alpha(R_{X,Y}^E V),$$

for all  $X, Y \in T_x M$ , for all  $V \in E_x$  and  $\alpha \in E_x^*$ .

#### Exercise 4

Let  $(M^n, g)$  be a Riemannian manifold and denote by  $\nabla$  resp.  $R$  the Levi-Civita connection resp. the Riemannian curvature tensor of  $(M^n, g)$ . Let the  $(0, 4)$ -tensor  $\tilde{R}$  be defined by  $\tilde{R}(X, Y, Z, W) := g(R(X, Y)Z, W)$ , for all  $X, Y, Z, W \in T_x M$  and  $x \in M$ .

- (a) Let  $x \in M$  be a point. Prove that the following identities are satisfied: for all  $X, Y, Z, T, U \in T_p M$ ,

$$(\nabla_X \tilde{R})(Y, Z, T, U) = -(\nabla_X \tilde{R})(Z, Y, T, U) = -(\nabla_X \tilde{R})(Y, Z, U, T) = (\nabla_X \tilde{R})(T, U, Y, Z).$$

- (b) For a given tensor field  $A \in \Gamma(T^*M \otimes T^*M)$  let the *divergence* of  $A$  be defined by

$$\text{div}(A)(X) := \sum_{j=1}^n (\nabla_{E_j} A)(E_j, X) \quad \forall X \in TM,$$

where  $\{E_j\}_{1 \leq j \leq n}$  is a local orthonormal basis of  $TM$ , that is,  $g(E_i, E_j) = \delta_i^j$ . Prove using the second Bianchi identity:

$$\text{div}(\text{ric}) = \frac{1}{2} d \text{scal}.$$

(Hint: for a given point  $x \in M$ , the basis  $\{E_j\}_{1 \leq j \leq n}$  can be chosen such that  $(\nabla E_i)|_x = 0$  holds; how can this be done?)

- (c) *Application:* Assuming  $n \geq 3$ , the manifold  $M$  connected and the existence of a smooth function  $f : M \rightarrow \mathbb{R}$  with  $\text{ric} = f \cdot g$  on  $M$ , prove that  $f$  is constant on  $M$ . Such a Riemannian manifold is then called *Einstein*.

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