

Recap: (M, g) Riem. mfd.

09.12.2020
! LECTURE ON DEC 10:
START: 10:45

→ metric on M : Riemannian distance function

1.5.3 VOLUME AND ORIENTATION

idea: (M, g) Riem. mfd. → $\text{vol}(M, g)$:

- locally: use charts and usual multivariable integration (measured via Riem. vol.)
- globally: sum up via partition of unity.

Remark. (integration on Riem. mfd's). Let (M, g) be a Riem. mfd, let $(\varphi_i: U_i \rightarrow U_i')$ $i \in I$ be a countable smooth atlas for M , let $(\psi_i)_{i \in I}$ be a partition of unity that is subordinate to $(\varphi_i)_{i \in I}$.

For $i \in I$, let $(g_{jk}^i)_{j, k \in \{1, \dots, n\}}$ be the local description of g w.r.t. φ_i .

- A map $f: M \rightarrow \mathbb{R}$ is measurable if f is measurable w.r.t. the Borel σ -algebra on \mathbb{R} and M .

(equivalently: for each $i \in I$, the map $f \circ \varphi_i^{-1}: \underbrace{U_i'}_{\subset \mathbb{R}^n} \rightarrow \mathbb{R}$ is measurable)

- A measurable map $f: M \rightarrow \mathbb{R}$ is integrable if

$$\sum_{i \in I} \int_{U_i} \psi_i(x) |f \circ \varphi_i^{-1}(x)| \sqrt{\det(g^i \circ \varphi_i^{-1}(x))} dx$$

$\in M_{n \times n}(\mathbb{R})$

is finite.

- For an integrable map $f: M \rightarrow \mathbb{R}$, we set

$$\int_M f d\mu_{M,g} := \sum_{i \in I} \int_{U_i} \psi_i \cdot f \circ \varphi_i^{-1} \sqrt{\det g^i \circ \varphi_i^{-1}} dx^n$$

integration
of char.
functions

measure $\mu_{M,g}$ on M .

Definition. (volume) let (M,g) be a Riem. wfd.
The volume of (M,g) is

$$\text{vol}(M,g) := \begin{cases} \int_M 1 d\mu_{M,g} & \text{if } 1: M \rightarrow \mathbb{R} \\ & \text{is integrable} \\ \infty & \text{otherwise.} \end{cases}$$

Example. let $n \in \mathbb{N}_{\geq 1}$ and $R \in \mathbb{R}_{>0}$. Then

$$\text{vol}(S^n(R), \text{round metr. of radius } R) = \frac{2 \cdot \pi^{\frac{n+1}{2}}}{\Gamma(\frac{n+1}{2} + 1)} \cdot R^n$$

$$\text{vol}(B_R^{\mathbb{R}^n, \text{Eucld.}}(0), \text{Eucld. Riem. metr.}) = \frac{\pi^{n/2}}{\Gamma(\frac{n}{2} + 1)} \cdot R^n$$

Questions: let $R, R_1, R_2 \in \mathbb{R}_{>0}$, $n \in \mathbb{N}_{\geq 1}$.

① When are $S^n(R_1)$ and $S^n(R_2)$ isometric? (locally isometric?)

② When are \mathbb{R}^n and $S^n(R)$ isometric?

③ When are \mathbb{R}^n and $S^n(R)$ locally isometric? *Real world problem: maps!*

④ When are $H^n(R_1)$ and $H^n(R_2)$ isometric? (locally isometric?)

⑤ When are \mathbb{R}^n and $H^n(R)$ isometric?

⑥ When are \mathbb{R}^n and $H^n(R)$ locally isometric?

Some answers:

①: Only if $R_1 = R_2$, because:
volume of Riemannian mfd's is invariant under Riemannian isometries! (transformation formula)

②: Never: $S^n(R)$ is compact but \mathbb{R}^n is not. Riem. isometries are homeomorphisms!

⑤, ⑥: Never:
Problem: \mathbb{R}^n and $H^n(R)$ have infinite volume!

no idea: compare volumes of metric balls.

Definition. (volume growth). let (M, g) be a Riem. mfd and let $x \in M$. The



volume growth function of M at x is

$$S_x^{(M, g)}: \mathbb{R}_{>0} \rightarrow \mathbb{R}_{\geq 0} \cup \{\infty\}$$

$$r \mapsto \mu_{M, g} \left(B_r^{M, g}(x) \right).$$

Proposition. (isometry invariance of volume growth), let $f: (M_1, g_1) \rightarrow (M_2, g_2)$ be a map and let $x \in M_1$. Then:

1. If f is an isometry, then $S_x^{(M_1, g_1)} = S_{f(x)}^{(M_2, g_2)}$.
2. If f is a local isometry, then there ex. an $\varepsilon \in \mathbb{R}_{>0}$ s.t.

$$\forall r \in [0, \varepsilon) \quad S_x^{(M_1, g_1)}(r) = S_{f(x)}^{(M_2, g_2)}(r).$$

Proof idea:

1. isometries map balls to balls (preserving the radius) and preserve the volume.
2. local isometries map balls of small enough radius to balls (preserving the radii).
Thus reduce to 1. \square

Back to (5)/(6): \mathbb{R}^n vs $H^n(\mathbb{R})$?!

• For each $x \in \mathbb{R}^n$, the function $S_x^{\mathbb{R}^n, \text{Eudid.}}$ is polynomial of degree n .

• There ex. $c_{n,\mathbb{R}}, a_{n,\mathbb{R}} \in \mathbb{R}_{>0}$ s.t.:

$$\forall x \in H^n(\mathbb{R}) \quad \forall r \in \mathbb{R}_{>0}$$

(6.2) $S_x^{H^n(\mathbb{R})}(r) \geq c_{n,\mathbb{R}} \cdot r^{n-1} \cdot a_{n,\mathbb{R}}$

and \mathbb{R}^n and $H^n(\mathbb{R})$ are not (locally) isometric.

Remark. The Riem. volume can also be expressed in terms of differential forms (on orientable mfd's).

If (M, g) is ~~a~~ ^{an oriented} Riem. mfd, then

$$\text{vol}(M, g) = \int_M \underbrace{\text{Vol}_{M, g}}_{\text{volume form of } (M, g)}$$

= locally: pull-back of the Euclidean volume form via orientation-preserving charts.

2

CURVATURE: FOUNDATIONS

Goal: give an intrinsic def. of curvature of Riem. mfd.

2.1

THE IDEA OF CURVATURE

Idea: Curvature quantifies how much a geometric object "bends" in comparison with "flat" Euclidean space. Intuitively, this should result in:



positive curvature



curvature 0



negative curvature

Possible approaches:

- ① Via curvature of curves
- ② Via angle sums in geodesic triangles
- ③ Via local and global properties of volume growth functions.

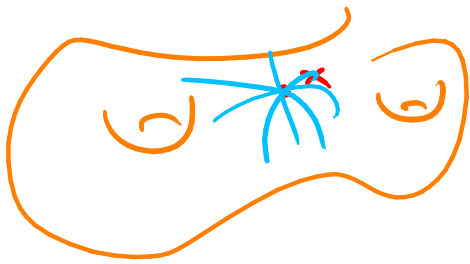
We follow ①. Assuming we have a notion of curvature of curves, how to define curvature of high-dim wfds ②

• curvature of Riem. surfaces (M, g) :

$$M \rightarrow \mathbb{R}$$

$x \mapsto$ (curvature of a curve through x)

• (maximal curvature)

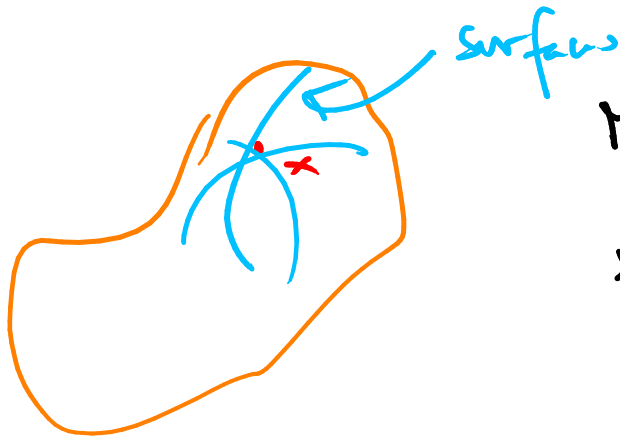


• curvature of high-dim Riem. wfd:

$$M \rightarrow \left(\begin{array}{c} \text{tangent} \\ \text{2-plane} \\ \text{at } x \end{array} \rightarrow \mathbb{R} \right)$$

$x \mapsto$ (curvature as above) at x

Corresp. to the tangent plane



Thus: How can we define "curvature of curves" ③

Use "acceleration", i.e., second derivatives!

→ How to define second derivatives?

Need: a way to differentiate vector fields (sections of vector bundles)

Two naive approaches:

① Second derivatives in local coordinates
are not independent of the charts!
(see example in the lecture notes).

② Higher ^{need connection terms} tangent bundles:

$\gamma: I \rightarrow M$ smooth curve

$\leadsto d\gamma: TI \rightarrow TM$ $\leadsto \dot{\gamma}: I \rightarrow TM$

$\leadsto d\dot{\gamma}: TI \rightarrow \underbrace{T(TM)}$

but: we want something
in TM !

\leadsto need to extract the correct part.

In the presence of a Riem. metric,
there is a canonical solution,

using connections on smooth vector
bundles.