

Recap: (linear) connections on a smooth mfd M

$$\nabla: \Gamma(TM) \times \Gamma(TM) \rightarrow \Gamma(TM)$$

properties:

$C^\infty(M)$ -linearity in first arg, \mathbb{R} -lin in the 2nd arg, product rule in 2nd arg:

$$\nabla_X (f \cdot Y) = X(f) \cdot Y + f \cdot \nabla_X Y$$

2.2.3 | COVARIANT DERIVATIVES ALONG CURVES

idea: connection on M \implies differentiate vector fields along curves in M in the direction of the velocity
"live on the curve, but with values in TM "

Definition. (extendable vector field). Let M be a smooth mfd and let $\gamma: I \rightarrow M$ be a smooth curve in M .

We write $\Gamma(TM|_\gamma)$:= set of all smooth maps $X: I \rightarrow TM$ with $X(t) \in T_{\gamma(t)}M$ vector fields in TM along γ

e.g. $\gamma \in \Gamma(TM|_\gamma) \quad \forall t \in I \quad X(t) \in T_{\gamma(t)}M$

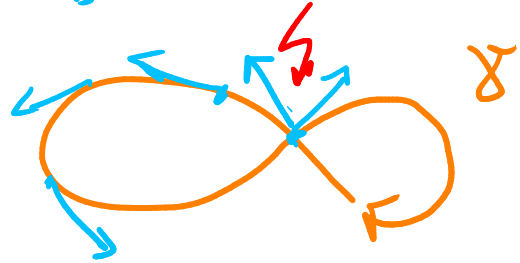
An $X \in \Gamma(TM|_\gamma)$ is extendable if there ex. an $\tilde{X} \in \Gamma(TM)$ with $\forall t \in I \quad X(t) = \tilde{X}(\gamma(t))$.

Example.

- extendable: • 0 vector field (e.g., by 0)



- not extendable:



Theorem. (covariant derivative along curves). Let

M be a smooth mfd, let ∇ be a linear connection on M , and let $\gamma: I \rightarrow M$ be a smooth curve in M . Then there ex. a

unique map $D_\gamma: \Gamma(TM|_\gamma) \rightarrow \Gamma(TM|_\gamma)$ with:

covariant derivative along γ .

- Compatibility with the connection: If $X \in \Gamma(TM|_\gamma)$ is extendable by $\tilde{X} \in \Gamma(TM)$, then

$$\forall t \in I \quad (D_\gamma X)(t) = (\nabla_{\dot{\gamma}(t)} \tilde{X})(\gamma(t)).$$

$\dot{\gamma}(t) \in T_{\gamma(t)} M$

- \mathbb{R} -linearity:

$$\forall \lambda_1, \lambda_2 \in \mathbb{R} \quad \forall X_1, X_2 \in \Gamma(TM|_\gamma) \quad D_\gamma(\lambda_1 X_1 + \lambda_2 X_2) = \lambda_1 \cdot D_\gamma(X_1) + \lambda_2 \cdot D_\gamma(X_2)$$

- Product rule:

$$\forall f \in C^\infty(I) \quad \forall X \in \Gamma(TM|_\gamma) \quad D_\gamma(f \cdot X) = f' \cdot X + f \cdot D_\gamma(X).$$

Proof "strategy": ① use \boxtimes to show locality of D_γ

uniqueness \leftarrow

② use \boxtimes and locality to derive a local formula

existence \leftarrow

③ show that everything that is constructed by the formula in ② satisfies \boxtimes and can be globalized

① as in the proof of locality of connections: use bump functions ...

② let $t \in I$ and let $\varphi: U \rightarrow U' \subset \mathbb{R}^n$ be a smooth chart around $\gamma(t) \in M$, let (E_1, \dots, E_n) be the corresponding frame for TM over U , and let $X \in \Gamma(TM|_U)$. Then: on a small enough interval $J \subset I$ around t , we can write

$$X|_J = \sum_{i=1}^n X^i \cdot E_i \circ \gamma$$

$J \rightarrow \mathbb{R}$ smooth

Then (if D_γ satisfies \boxtimes)

$$D_\gamma X(t) \stackrel{\text{①}}{=} \sum_{i=1}^n D_\gamma (X^i \cdot E_i \circ \gamma)(t)$$

+ linearity

product rule

$$= \sum_{j=1}^n (X^{j'}(t) \cdot E_j \circ \gamma(t) + X^j(t) \cdot D_\gamma (E_j \circ \gamma)(t))$$

extendable on U by E_j

compatibility

$$= \sum_{j=1}^n (X^{j'}(t) \cdot E_j \circ \gamma(t) + X^j(t) \cdot (\nabla_{\dot{\gamma}(t)} E_j)(\gamma(t)))$$

only contains given data! \square ②

$$\boxed{**} \left\{ \begin{aligned} &= \sum_{j=1}^n X^{j'}(t) \cdot E_j \circ \gamma(t) \\ &+ \sum_{k=1}^k \sum_{i=1}^n \sum_{j=1}^n \gamma^{i'}(t) \cdot X^j(t) \cdot \Gamma_{ij}^k(\gamma(t)) \cdot E_k \circ \gamma(t) \end{aligned} \right.$$

③. Use $\boxed{**}$ to define D_γ on chart domains

- check that in each chart domain \mathbb{R}^n is satisfied.

- by ① and ②: these definitions are compatible on the intersection of their domains

\leadsto can define $D_\gamma : \Gamma(\pi^{-1}(\gamma)) \rightarrow \Gamma(\pi^{-1}(p))$

- check that \mathbb{R}^n is satisfied. \square

Example. (covariant derivatives along curves).

- in \mathbb{R}^n , with the Euclidean linear connection $\bar{\nabla}$:

let $\gamma: I \rightarrow \mathbb{R}^n$ be a smooth curve. Then

$$\forall_{t \in I} (D_\gamma \dot{\gamma})(t) = \gamma''(t).$$

Concrete examples:

- $\gamma: I \rightarrow \mathbb{R}^n$ (given $a, b \in \mathbb{R}^n$)
 $t \mapsto a + t \cdot (b - a)$

$\leadsto D_\gamma \dot{\gamma} = 0.$



- $\gamma: I \rightarrow \mathbb{R}^2$
 $t \mapsto (\cos t, \sin t)$

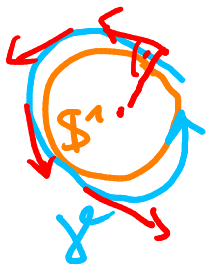
$\leadsto \forall t \in I (D_\gamma \dot{\gamma})(t) = (-\sin t, \cos t) \neq 0.$

- $S^1 \subset \mathbb{R}^2$ with the linear connection ∇^T on S^1 induced from ∇ on \mathbb{R}^2 :

We consider

$$\gamma: \mathbb{R} \rightarrow S^1$$

$$t \mapsto (\cos t, \sin t).$$



What is $D_\gamma \dot{\gamma}$ (?) $\underbrace{\hspace{10em}}_{=: X \in \Gamma(TS^1|_\gamma)}$

X is extendable, even to \mathbb{R}^2 , by:

$$\tilde{X}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$(x, y) \mapsto (-y, x)$$

Then:

$$\boxed{(D_\gamma \dot{\gamma})(t)} = \underbrace{\hspace{10em}}_{\text{compatibility with the connection}} (\nabla_X^T \tilde{X}|_{S^1})(\gamma(t))$$

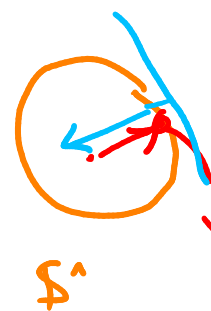
orth.

projection onto $T_{\gamma(t)} S^1 = P_{\gamma(t)} \left((\nabla_X \tilde{X})(\gamma(t)) \right)$

$$= P_{\gamma(t)} \left(-\sin t \cdot (\nabla_{E_1} \tilde{X})(\gamma(t)) + \cos t \cdot (\nabla_{E_2} \tilde{X})(\gamma(t)) \right)$$

$T_{\gamma(t)} \mathbb{S}^1$

$$= P_{\gamma(t)} \left(-\sin t \cdot (0, 1) + \cos t \cdot (-1, 0) \right)$$



$$= P_{\gamma(t)} \left(-\cos t, -\sin t \right)$$

$$= 0.$$

$$\gamma(t) = (\cos t, \sin t)$$

\mathbb{S}^1

2.2.4 GEODESICS

idea: given a connection ∇

$\xrightarrow{2.2.3}$ covariant derivatives along curves

in particular: can define acceleration of curves as $D_{\dot{\gamma}} \dot{\gamma}$.

in \mathbb{R}^n : straight lines are exactly the curves with 0 acceleration

$\xrightarrow{\quad}$ turn this property into a def!

DE: Geodätische / Geodäte

Definition (geodesic) let M be a smooth manifold with a linear connection ∇ and let $\gamma: I \rightarrow M$ be a smooth curve in M .

Then γ is a geodesic (wrt ∇) if

$$D_{\dot{\gamma}} \dot{\gamma} = 0, \quad \rightarrow \text{differential eq}$$

Example. (see previous example)

- in \mathbb{R}^n : geodesics (wrt Euclidean linear connection) are exactly the straight lines of the form $t \mapsto a + t \cdot (b-a)$.

In particular: $\gamma: t \mapsto (\cos t, \sin t)$ is not a geodesic in \mathbb{R}^2 (wrt $\bar{\nabla}$).

- on S^1 : $\gamma: t \mapsto (\cos t, \sin t)$ is a geodesic (wrt ∇^T).

Remark. (geodesic equation). Let M be a smooth manifold with a linear connection ∇ and let $\gamma: I \rightarrow M$ be a smooth curve.

Then γ is a geodesic wrt ∇ if and only if γ locally satisfies (follows from ~~**~~)

$$\forall \left(\begin{array}{l} \text{"} \\ \nabla_s \\ \text{"} \\ k \in \{1, \dots, n\} \end{array} \right) \gamma^k(s) + \sum_{i=1}^n \sum_{j=1}^n \gamma^{i1}(s) \cdot \gamma^{j1}(s) \cdot \Gamma_{ij}^k(\gamma(s)) = 0$$

second order ODE.