

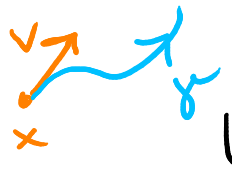
Org.: next lectures: 23.12., 07.01.

- (optional) bonus exc sheet \leftarrow material will appear in the next days
- lin. connection ∇

Recap: • geodesic: $\overset{\text{lin. connection}}{\mathbb{D}}_{\dot{\gamma}} \dot{\gamma} = 0$

• geodesic equation: $\nabla_{\dot{\gamma}} \dot{\gamma} = 0 \iff \sum_k \ddot{\gamma}^k + \sum_i \sum_j \dot{\gamma}^i \dot{\gamma}^j \Gamma_{ij}^k = 0$
(2nd order ODE)

Theorem. (existence and uniqueness of geodesics). Let M be a smooth mfd, let ∇ be a lin. connection on M , let $x \in M$, let $v \in T_x M$, and let $t \in \mathbb{R}$. Then: There is an interval $I \subset \mathbb{R}$ with $t \in I^0$ and a geodesic $\gamma: I \rightarrow M$ (wrt ∇) with $\gamma(t) = x$ and $\dot{\gamma}(t) = v$.



Uniqueness: If $\gamma: I \rightarrow M$ and $\eta: J \rightarrow M$ are geodesics with $t \in I^0 \cap J^0$ and $\gamma(t) = x = \eta(t)$ and $\dot{\gamma}(t) = v = \dot{\eta}(t)$, then $\gamma|_{I \cap J} = \eta|_{I \cap J}$.

Proof. • This is a local problem.
• Geodesics are characterised by the geodesic equation, a 2nd order ODE; the constraints " $\gamma(t) = x$ and $\dot{\gamma}(t) = v$ " give the correct number of initial conditions.

\rightarrow Apply ODE theory. □

Definition (maximal geodesic). Let M be a smooth manifold with a linear connection ∇ . A smooth curve $\gamma: I \rightarrow M$ is a maximal geodesic if γ is a geodesic wrt ∇ and if there is no geodesic $\eta: J \rightarrow M$ wrt ∇ with $I \subset J$ and $\eta|_I = \gamma$ but $J \neq I$.

Corollary. (existence and uniqueness of maximal geodesics). Let M be a smooth manifold, let ∇ be a linear connection on M , let $x \in M$, and $v \in T_x M$. Then there is a unique maximal geodesic $\gamma: I \rightarrow M$ with $0 \in I$ and $\gamma(0) = x$ and $\dot{\gamma}(0) = v$.

Notation: $\text{geod}_{x,v}$

Proof. previous thm + standard ODE arguments \square (7.2)

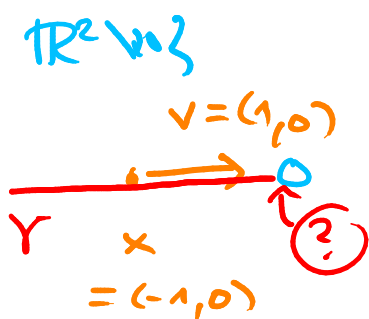
Examples: (maximal geodesics).

- in \mathbb{R}^n (with the Euclidean lin. connection), the maximal geodesics are exactly the (lin. parametrized) affine lines.

of the form: $\mathbb{R} \rightarrow \mathbb{R}^n$
 $t \mapsto x + t \cdot v$

- a maximal geodesic, whose domain is not all of \mathbb{R} :

We consider $\mathbb{R}^2 \setminus \{0\}$ with the Euclidean lin. connection.



let $x := (-1, 0)$, $v := (1, 0)$. Then

$$\text{geod}_{x,v}^{\mathbb{R}^2 \setminus \{0\}} : (-\infty, 1) \rightarrow \mathbb{R}^2 \setminus \{0\}$$

$$t \mapsto x + t \cdot v.$$

(compare with $\mathbb{R}^2 \dots$)

2.2.5 PARALLEL TRANSPORT

idea: vector fields along curves are considered parallel if their covariant derivative is zero.

\leadsto can use parallel vector fields to move between different tangent spaces.

\leadsto "geometric" description of connections

Definition. (parallel vector field). Let M be a smooth mfd with a lin. connection ∇ , and let $\gamma \in \Gamma(TM|_U)$. Then X is parallel along γ (wrt ∇) if

$$D_\gamma X = 0.$$

($\leadsto \gamma$ is a geodesic $\iff \gamma$ is parallel along γ)

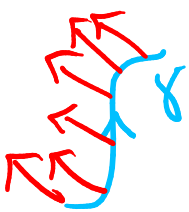
Remark. (parallel transport equation). In the situation of the definition, X is parallel along γ

if and only if locally we have

$$X^{k'} = - \sum_i \sum_j X^{\dot{j}} \cdot \underbrace{\gamma^{i|}}_{\text{indep of } X} \cdot \Gamma_{ij}^k \circ \gamma$$

(linear 1st order ODE with smooth coefficients!)

Example. In \mathbb{R}^n with the Euclidean linear connection, vector fields along curves are parallel if and only if they are "constant".

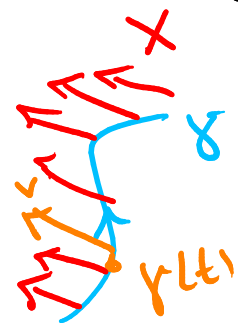


(the connection coeffs wrt standard coord. frame are all 0).

Theorem. (existence and uniqueness of parallel vector fields). Let M be a smooth mfd with a lin. connection ∇ , let $\gamma: I \rightarrow M$

be a smooth curve, let $t \in I$, and let $v \in T_{\gamma(t)} M$. Then: There ex. a unique vector field $X \in \Gamma(TM|_{\gamma})$ with

$X(t) = v$ and X is parallel along γ (wrt ∇).

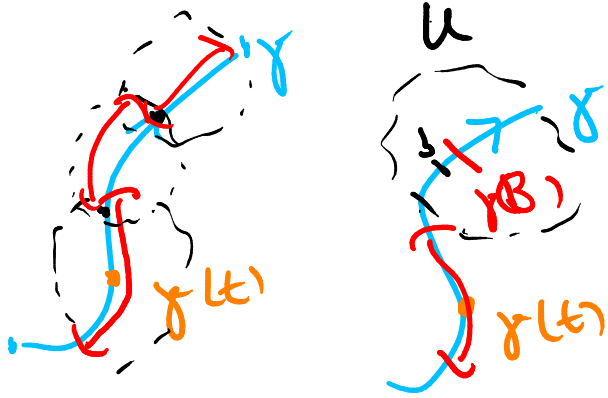


Proof. • Local step: If γ is contained in a single chart domain, then: apply ODE

theory to the parallel transport (eq), which is a linear 1st order ODE with smooth coeff's.

• Global step:

global solution!
let $\neq \emptyset$ (by local step)



$B := \sup \{ b \in I \mid \text{there ex. a solution on } [t, b] \}$

Goal: show that $B = \sup I$.

Assume for a contradiction that $B \neq \sup I$.

let U be a chart domain around $y(B)$.

\rightarrow there ex. $b \in (t, B)$ and $\varepsilon \in \mathbb{R}_{>0}$ s.t.

$y(\underbrace{(b-\varepsilon, b+\varepsilon)}_{=: J}) \subset U$. and $b+\varepsilon < B$.

Consider the local problem at $b - \frac{1}{2}\varepsilon$.

let X be a solution on $[t, B]$.

Use the local step at time $b - \frac{1}{2}\varepsilon$

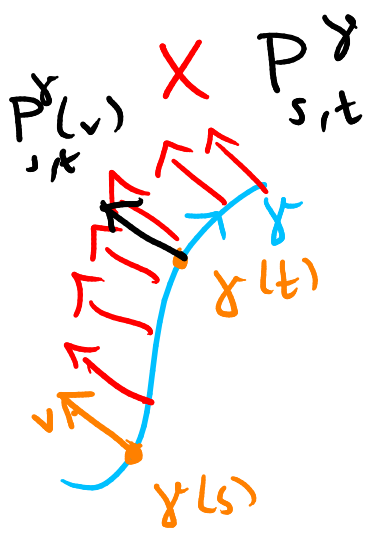
with direction $X(b - \frac{1}{2}\varepsilon)$.

local step \rightarrow can extend the solution on U .

\rightarrow can extend past B ∇ . \square

Definition. (parallel transport). let M be a smooth mfd with lin. connection ∇ , let $\gamma: I \rightarrow M$

be a smooth curve, and let $s, t \in I$.
 Then the parallel transport along γ from s to t (wrt ∇) is:



$$P_{s,t}^{\gamma} : T_{\gamma(s)} M \longrightarrow T_{\gamma(t)} M$$

$v \longmapsto X(t)$, where X is the unique parallel vector field along γ with $X(s) = v$.

Proposition. Let M be a smooth manifold with lin. conn. ∇ , let $\gamma: I \rightarrow M$ be a smooth curve, and let $s, t \in I$. Then

$$P_{s,t}^{\gamma} : T_{\gamma(s)} M \longrightarrow T_{\gamma(t)} M$$

is an \mathbb{R} -lin. isomorphism.

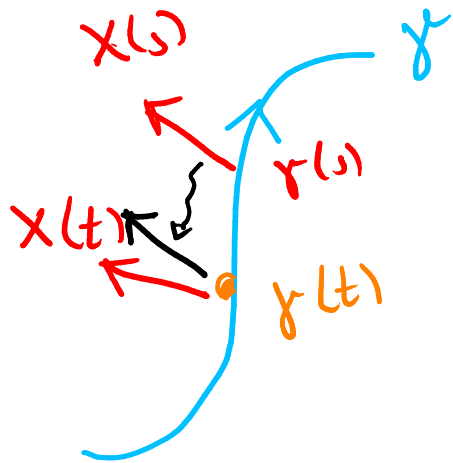
Proof.: • \mathbb{R} -lin.: \mathbb{R} -lin. modification of initial values of a lin. SDE
 • iso: $P_{t,s}^{\gamma}$ is the inverse
 (use the same parallel vector field). \square

Theorem. (cov. derivative along curves via parallel transport). Let M be smooth manifold with a lin. conn. ∇ , let $\gamma: I \rightarrow M$ be a smooth

curve, and let $t \in I$. Then

$$\forall X \in \Gamma(TM|_y) \quad (\mathbb{D}_\gamma X)(t) = \lim_{s \rightarrow t} \frac{P_{s,t}^\gamma(X(s)) - X(t)}{s - t}$$

"differential quotient"



Proof. idea: express both sides in terms of a parallel frame.

let (E_1, \dots, E_n) be a parallel frame of TM along γ . \uparrow
 E_1, \dots, E_n parallel along γ \rightarrow basis at each pt.

exists: choose a basis of $T_{\gamma(t)}M$,

extend it to parallel vector fields \rightarrow at each pt a basis, because parallel transport gives lin. isms.

\rightarrow can write $X = \sum_{j=1}^n X^j \cdot E_j$.

$\Gamma(TM|_\gamma) \quad I \rightarrow \mathbb{R}$ smooth

$$\text{LHS: } \boxed{\mathbb{D}_\gamma X} = \sum_{j=1}^n \mathbb{D}_\gamma (X^j \cdot E_j) \quad \begin{matrix} E_j \text{ parallel} \\ = 0 \end{matrix}$$

$$= \sum_{j=1}^n (X^j \cdot E_j + X^j \cdot \mathbb{D}_\gamma(E_j))$$

$$= \left| \sum_{j=1}^n X^{j'} \cdot E_j \right|$$

RHS: For all $s \in I$:

$$\left| P_{s,t}^\delta (X(s)) \right| = \sum_{j=1}^n X^{j(s)} \cdot P_{s,t}^\delta (E_j(s))$$

$= E_j(t)$: E_j parallel

$$= \left| \sum_{j=1}^n X^{j(s)} \cdot E_j(t) \right|$$

\leadsto take differential quotient. □

\leadsto allows to rewrite ∇ in terms of parallel transport. \bar{u}