

Recap: $T^{k,l}M = (TM)^{\otimes k} \otimes_{\mathbb{R}} (T^*M)^{\otimes l}$

$T^{2,0}M \cong TM \otimes_{\mathbb{R}} TM$

1.3 RIEMANNIAN MANIFOLDS

idea: there are many approaches to Euclidean geo-
(e.g., axiomatically or computationally)

covariant 2-tensor on \mathbb{R}^n that is symmetric and pos. definite $\xrightarrow{\text{linear algebra: } \mathbb{R}^n \text{ + Euclidean}}$ inner product

• Riemannian manifold: smooth mfd + "smooth" family of inner products on the tangent spaces.

1.3.1 RIEMANNIAN METRICS

Definition. (Riemannian metric), let M be a smooth mfd. A Riemannian metric on M is a $g \in \Gamma(T^{2,0}M)$ with:
a section

- symmetry: $\forall x \in M \forall v, w \in T_x M \quad g_x(v \otimes w) = g_x(w \otimes v)$
- positive definite: $\forall x \in M \forall v \in T_x M \quad g_x(v \otimes v) > 0$.

and write $\langle \cdot, \cdot \rangle_x : T_x M \times T_x M \rightarrow \mathbb{R}$
 $(v, w) \mapsto g_x(v \otimes w)$
(is an inner product on $T_x M$).

Example. (Euclidean space). let $n \in \mathbb{N}$. Then

$$\mathbb{R}^n \rightarrow T^{2,0}\mathbb{R}^n$$

$x \mapsto$ standard Euclidean inner product on $\mathbb{R}^n \cong T_x \mathbb{R}^n$
↑ canonical iso

is a Riemannian metric on \mathbb{R}^n , the Euclidean Riemannian metric.

(similarly for open subsets of \mathbb{R}^n)

goal: every smooth manifold admits a Riemannian metric

strategy:

- locally: use smooth charts to pullback the Euclidean Riemannian metric
- globally: glue these via a partition of unity.

Proposition. (pullback of Riemannian metrics). let $f: M \rightarrow N$ local diffeomorphism (smooth immersion) and let g be a Riemannian metric on N . Then: f^*g is a Riemannian metric on M , where

$$f^*g: M \rightarrow T^{2,0}M$$

$$x \mapsto \begin{pmatrix} \psi & \psi \\ \nu \otimes \nu \end{pmatrix} \begin{matrix} T_x M & T_x M \\ \downarrow & \downarrow \\ \psi & \psi \end{matrix}$$

$$\in T_{f(x)}N$$

$$\downarrow$$

$$g \quad (d_x f \nu \otimes d_x f \nu)$$

Proof: • $f^*g \in \Gamma(T^{2,0}M)$, because $g \in \Gamma(T^{2,0}N)$ and f is smooth

• symmetry: because g is symmetric

• positive definiteness: let $x \in M$ and $v \in T_x M$ ~~10~~

Then:

$$(f^*g)_x(v \otimes v) = g_{f(x)}(d_x f(v) \otimes d_x f(v))$$

$g_{f(x)}$ is pos. definite

$$\rightarrow \boxed{> 0}$$

$\neq 0$ because $v \neq 0$ and f is a local diffeomorphism \square

Proposition. (scaling of Riem. metrics). Let M be a smooth mfd, let $g_1, g_2 \in \text{Riem}(M)$, let $f_1, f_2 \in C^\infty(M, \mathbb{R}_{>0})$ with $f_1 + f_2 > 0$.

Then

$$f_1 g_1 + f_2 g_2 : M \rightarrow T^{2,0} M$$

$$x \mapsto (v \otimes w \mapsto f_1(x) \cdot (g_1)_x(v \otimes w) + f_2(x) \cdot (g_2)_x(v \otimes w))$$

$\in \mathbb{R}_{>0}$
pointwise

is a Riemannian metric on M .

Proof. (ii) 3.2 \square

Theorem. (existence of Riem. metrics). Every smooth mfd admits a Riemannian metric.

Proof. (use the strategy above!). Let M be a smooth mfd of dim n . Then there ex. a family $(\varphi_i : U_i \rightarrow U'_i)_{i \in I}$ of smooth charts on M with $\bigcup_{i \in I} U_i = M$.

$U'_i \subset \mathbb{R}^n$

• local step: let $i \in I$, let g_i be the Euclidean Riem. metric on $U'_i \subset \mathbb{R}^n$.

Then $\psi_i^* g_i$ is a Riem. metric on U_i
 (as a smooth chart $\psi_i: U_i \rightarrow \mathbb{R}^n$ is
 a diffeo!)



- global step: let $(\psi_i)_{i \in I} \in C^\infty(M, \mathbb{R}_{\geq 0})$ be a partition of unity of M that is subordinate to $(U_i)_{i \in I}$.
- for all $i \in I$: $\text{supp } \psi_i \subset U_i$
- local finiteness: for all $x \in M$, the set $\{i \in I \mid \psi_i(x) \neq 0\}$ is finite
- $\forall x \in M \quad \sum_{i \in I} \psi_i(x) = 1$.

Then: $\sum_{i \in I} \psi_i \cdot \psi_i^* g_i$ is a Riem. metric on M . \square

Corollary. (non-uniqueness of Riem. metrics).

Let M be a non-empty smooth mfd.

Then $\text{Riem}(M)$ is uncountable. *of non-zero dim!*

Proof. By the theorem, there ex. a Riem. metric g on M . By scaling, for each $f \in C^\infty(M, \mathbb{R}_+)$, also $f \cdot g$ is a Riem. metric on M . uncountable as $M \neq \emptyset$. \square
as dim $M \neq 0 \rightarrow$ changes with f

Remark. (Riemannian metrics in local coordinates).
 let M be a smooth mfd of dim n , let
 $\varphi: U \rightarrow U' \subset \mathbb{R}^n$ be a smooth chart of M ,
 and let $x^1, \dots, x^n: U \rightarrow \mathbb{R}$ be the
 assoc. coord. functions of φ .

$\leadsto (dx^i \otimes dx^j)_{i,j \in \{1, \dots, n\}}$ is a local
 frame of $\underbrace{T^{2,0}M}_{\cong (T^*M \otimes_{\mathbb{R}} T^*M)}$ over U .

\leadsto every Riem. metric g on M can be
 written as $g = \sum_{i,j} g_{ij} dx^i \otimes dx^j$

$$g|_U = \sum_{i,j \in \{1, \dots, n\}} g_{ij} \cdot dx^i \otimes dx^j$$

with $(g_{ij} \in C^\infty(U, \mathbb{R}))_{i,j \in \{1, \dots, n\}}$.

For each $x \in U$, the $(g_{ij}(x))_{i,j \in \{1, \dots, n\}}$
 is symmetric and pos. definite. $\in M_{n \times n}(\mathbb{R})$

works
 also
 this
 way

Example. • Euclidean Riemannian metric on \mathbb{R}^n
 in standard coordinates x^1, \dots, x^n :

$$\begin{aligned} \sum_{i,j \in \{1, \dots, n\}} \delta_{ij} dx^i \otimes dx^j &= \sum_{i,j} \delta_{ij} dx^i dx^j \\ &= \sum_{i=1}^n dx^i \otimes dx^i \\ &= \sum_{i=1}^n (dx^i)^2. \end{aligned}$$

gets smaller
if x^2
gets larger

$$\frac{1}{(x^2)^2 + 1} \cdot ((dx^1)^2 + (dx^2)^2)$$

is a Riem. metric on \mathbb{R}^2
(rescaling of Euclidean Riem. metric).

on \mathbb{R}^2 :

$(dx^1)^2 - (dx^2)^2$ is no Riem. metric
on \mathbb{R}^2 (it's not pos. def.)

1.3.2 RIEMANNIAN MANIFOLDS

Definition. (Riemannian mfd). A Riemannian mfd is a pair (M, g) , consisting of a smooth mfd M and a Riem. metric g on M .

Example. $(\mathbb{R}^n, \text{Euclidean Riem. metric})$.

Example. (first fundamental form) let $N \in \mathbb{N}$
and let $M \subset \mathbb{R}^N$ be a smooth submfd.
Then the Euclidean Riem. metric on \mathbb{R}^N
induces a Riemannian metric on M
(via the geometric spaces), the first fundamental form on M .

\rightarrow Riem. metric on $S^n \subset \mathbb{R}^{n+1}$, the round Riem. metric on S^n .

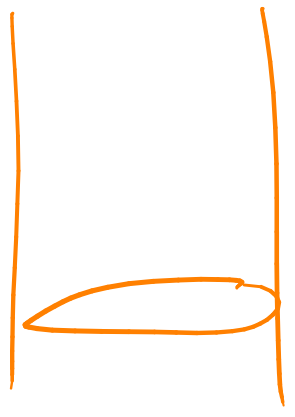
Example. (products).

Warped \leftarrow DE: verzerrtes Produkt

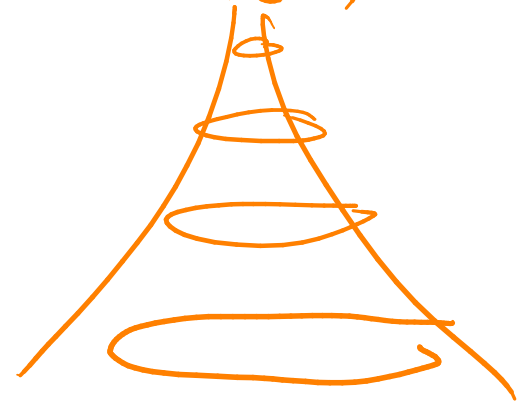
(M_1, g_1) Riem. mfd's $\rightarrow (M_1 \times M_2,$
 (M_2, g_2) $(x, y) \mapsto (g_1)_x + f^2(w) \cdot (g_2)_y$)
 Riem mfd

$f \in C^\infty(M_1, \mathbb{R}_{>0})$

$S^1 \times \mathbb{R}_{>0}$



$S^1 \times (t \mapsto e^{-t}) \mathbb{R}_{>0}$



$(S^1 \times S^1, \text{round} \oplus \text{round})$: 2-torus



(geometry is not well reflected in this picture).

Definition. (local) isometries. let $(M, g), (M', g')$ be Riem. mfd's.

• A local isometry $(M, g) \rightarrow (M', g')$

$\text{Isom}(M, g)$ is a local diffeo $f: (M, g) \rightarrow (M', g')$

with $f^*g' = g$.

• An isometry $(M, g) \rightarrow (M', g')$ is a diffeo $f: (M, g) \rightarrow (M', g')$ with $f^*g' = g$.