

Recap: exponential map:

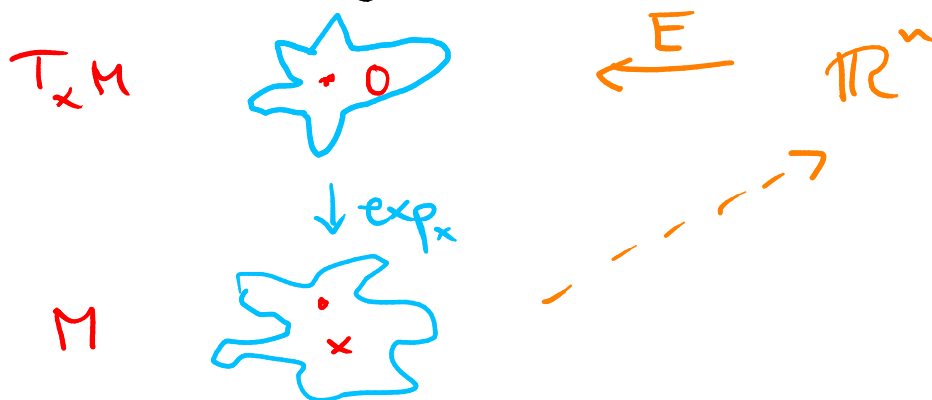
$(M, g)$  Riem. mfd  
 $x \in M \rightarrow$

$T_x M$   
 $\text{Exp}_x^U \xrightarrow{\exp_x} M$   
 $\downarrow \quad \longmapsto \text{grad}_{x,v}(1)$

### 3.1.2 NORMAL COORDINATES

Definition. (normal nbhd, normal coord's). Let  $(M, g)$  be a Riem. mfd, let  $x \in M$ .

- An open nbhd  $U \subset M$  of  $x$  is normal if it is the diffeomorphic image under  $\exp_x$  of an open star-shaped (wrt  $0 \in T_x M$ ) set in  $T_x M$ .



- Let  $U \subset M$  be a normal nbhd of  $x$ , let  $(v_1, \dots, v_n)$  be an orthonormal basis of  $T_x M$ , and let  $E: \mathbb{R}^n \rightarrow T_x M$  be the  
 $(x^1, \dots, x^n) \mapsto \sum_{j=1}^n x^j \cdot v_j$  corr. exp. iso.

Then

$$E^{-1} \circ \exp_x|_U : U \rightarrow \mathbb{R}^n$$

is a normal coordinate chart around  $x$ .

Remark. If  $(M, g)$  is a Riem. mfd and  $x \in M$ , then there ex. normal nbhd/normal wood's around  $x$  (because exp is a local diffeo).

Definition. (geodesic ball) let  $(M, g)$  be a Riem mfd, let  $x \in M$ , let  $r \in \mathbb{R}_{>0}$  with  $B_r^{T_x M, g_x}(0) \subset \text{Exp}_x$ .

Then  $\text{ball}_r^{M, g}(x) := \exp_x(B_r^{T_x M, g_x}(0)) \subset M$  is the geodesic ball of radius  $r$  at  $x$ .

Warning: So far, it is not clear how geodesic balls are related to metric balls (wrt Riem. distance function)!

Proposition. (uniformly normal nbhds). Let  $(M, g)$  be a Riem. mfd, let  $x \in M$ . Then  $x$  admits a uniformly normal nbhd, i.e., there ex.



an open nbhd  $U \subset M$  of  $x$  s.t. there ex. an  $r \in \mathbb{R}_{>0}$  with: for each  $y \in U$ , we have that  $U \subset \text{ball}_r^{M, g}(y)$  and  $\text{ball}_r^{M, g}(y)$  is a normal nbhd of  $y$ .

Proof. This about compactness...

□

Proposition. (initial data for isometries). Let  $(M, g)$  be a connected Riemann manifold and let  $\varphi, \psi \in \text{Isom}(M, g)$ .  
 Moreover,  $\xrightarrow{\text{path-connected}}$  let  $x \in M$  with

$$\varphi(x) = \psi(x) \text{ and } d_x \varphi = d_x \psi.$$

Then:  $\varphi = \psi$ .

Proof. idea: use uniqueness/naturality of geodesics.

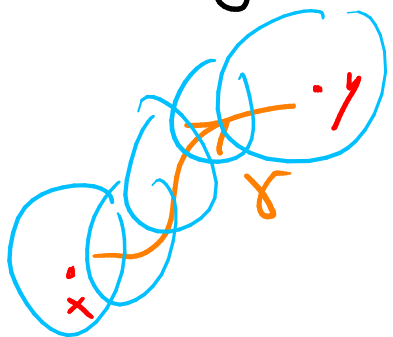
Wlog: can consider the case that  $\varphi(x) = x$  and  $d_x \varphi = \text{id}_{T_x M}$  and show  $\varphi = \text{id}_M$ .  
 hold  $\varphi = \psi^{-1}$

① Special case:  $M$  is a uniformly normal nbhd of  $x$ . let  $y \in M$ , say  $y = \exp_x(v)$  with  $v \in T_x M$ . Then

$$\begin{aligned} \varphi(y) &= \varphi(\exp_x(v)) \stackrel{\text{naturality of exp}}{=} \exp_{\varphi(x)}(\underbrace{d_x \varphi(v)}_{=v}) \\ &= \exp_x(v) = y. \end{aligned}$$

② general case: let  $y \in M$ . let  $\gamma$  be a path from  $x$  to  $y$  (ex.!).

We can cover  $\text{im } \gamma$  by finitely many uniformly normal nbhds, then apply ①. □



successively

## B.2 RIEMANNIAN GEODESICS

goal: relate geodesics to (locally) minimizing curves

idea: don't work on the space of all curves with given endpoints, but only look at one-parameter families of curves.  
 ↳ variations

### 3.2.1 VARIATIONS OF CURVES

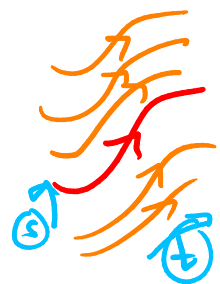
Definition. (piecewise regular families). Let  $M$  be a smooth manifold, let  $a, b \in \mathbb{R}$  with  $a < b$ , let  $\varepsilon \in \mathbb{R}_{>0}$

• A map  $G: (-\varepsilon, \varepsilon) \times [a, b] \rightarrow M$  is piecewise smooth if  $G$  is continuous and if there ex.  $k \in \mathbb{N}$ ,  $a = a_0 < a_1 < \dots < a_k = b$

s.t.  $G|_{(-\varepsilon, \varepsilon) \times [a_j, a_{j+1}]}$

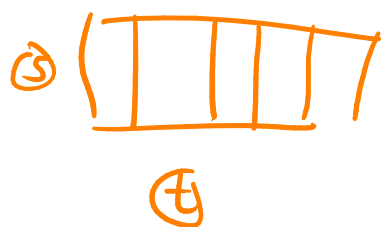
is smooth for each  $j \in \{1, \dots, k-1\}$ .

• A piecewise smooth map  $G: (-\varepsilon, \varepsilon) \times [a, b] \rightarrow M$  is a piecewise regular family of curves if for each  $s \in (-\varepsilon, \varepsilon)$ , the map  $G(s, \cdot)$  is a piecewise regular curve.



$$(-\varepsilon, \varepsilon) \times [a, b] \rightarrow M$$

$s \quad t$



Remark. Let  $M$  be a smooth manifold and let  $G: (-\varepsilon, \varepsilon) \times [a, b] \rightarrow M$  be a piecewise regular family of curves. We then write

in general, family of curves. We then write

not everywhere def'd  $\rightarrow \partial_{(2)} G(s, t) := (G(s, \cdot))'(t)$

def'd everywhere  $\rightarrow \partial_{(1)} G(s, t) := (G(\cdot, t))'(s)$ , wherever they are defined.

Proposition. (Symmetry lemma for variations). Let  $(M, g)$  be a Riem. manifold, let  $G: (-\varepsilon, \varepsilon) \times [a, b] \rightarrow M$  be a piecewise regular family. Then: On every neighborhood  $Q = (-\varepsilon, \varepsilon) \times [a, b] \subset (-\varepsilon, \varepsilon) \times [a, b]$  on which  $G$  is smooth, we have

$$\forall (s, t) \in Q \left( \underset{G(\cdot, t)}{D} \partial_{(2)} G \right)(s, t) = \left( \underset{G(s, \cdot)}{D} \partial_{(1)} G \right)(s, t).$$

Proof. This is a consequence of the symmetry of the LC-connection: We prove the prop. in local coord's. In suitable small nbhds in  $Q$ , we can write

$$\partial_{(2)} G = \sum_{k=1}^n \partial_2 x^k \cdot E_k$$

$\leftarrow$  local coord  
 $\leftarrow$  local frame

$$\partial_{(1)} G = \sum_{k=1}^n \partial_1 x^k \cdot E_k.$$

Then:

$$D_{G(\cdot, t)} \partial_2 G(s, t) = \sum_{k=1}^n \partial_1 \partial_2 x^k(s, t) \cdot E_k(G(s, t)) + \sum_{i, j, k=1}^n \partial_2 x^i(s, t) \cdot \partial_1 x^j(s, t) \cdot \Gamma_{ij}^k(G(s, t))$$

(x<sup>k</sup> smooth)

$$D_{G(s, \cdot)} \partial_1 G(s, t) = \sum_{k=1}^n \partial_2 \partial_1 x^k(s, t) \cdot E_k(G(s, t)) + \sum_{i, j, k=1}^n \partial_1 x^i(s, t) \cdot \partial_2 x^j(s, t) \cdot \Gamma_{ij}^k(G(s, t))$$

LC-conn is symmetric.

Definition. (variation of a curve). Let  $M$  be a smooth manifold and let  $\gamma: [a, b] \rightarrow M$  be a piecewise regular curve.

A variation of  $\gamma$  is a pw regular family  $G: (-\varepsilon, \varepsilon) \times [a, b] \rightarrow M$  of curves with  $G(0, \cdot) = \gamma$ .

Such a variation is proper if



$$\forall s \in (-\varepsilon, \varepsilon)$$

$$G(s, a) = \gamma(a) \text{ and}$$

$$G(s, b) = \gamma(b).$$

variation field

## 3.2.2 VARIATION FIELDS AND THE FIRST VARIATION FORMULA

idea: look at the "vertical" change of curves

Definition. (variation field). Let  $M$  be a smooth manifold, let  $G$  be a variation of a pm regular curve  $\gamma: [a, b] \rightarrow M$ . The variation field of  $G$  is the vector field

$$\begin{aligned} [a, b] &\rightarrow TM \\ t &\mapsto \partial_{\partial_t} G(0, t) \end{aligned}$$

along  $\gamma$ .

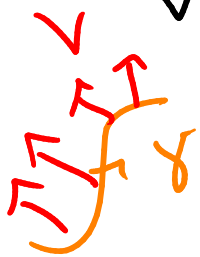
Proposition. (existence of variation fields). Let  $(M, g)$  be a Riemann manifold, let  $\gamma: [a, b] \rightarrow M$  be a pm regular curve, and let  $V$  be a smooth vector field along  $\gamma$ . Then  $V$  is the variation field of some variation of  $\gamma$ .

If  $V(a) = 0 = V(b)$ , then  $V$  is the variation field of a proper variation of  $\gamma$ .

Proof. Idea: take

$$G: (s, t) \mapsto \exp_{\gamma(t)}(s \cdot V(t)).$$

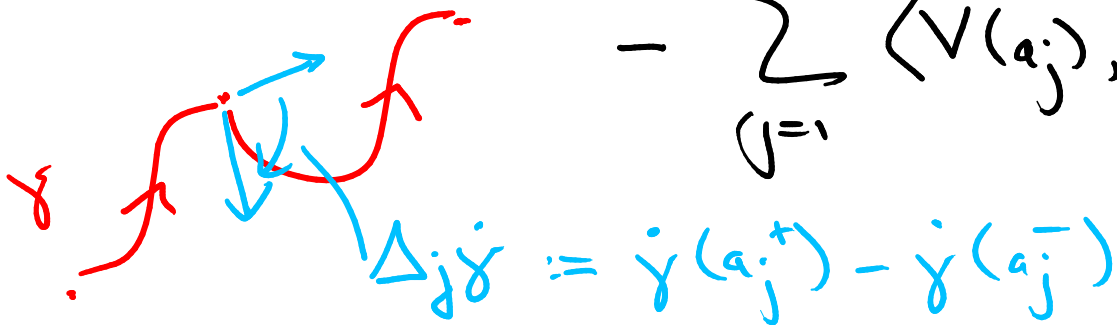
( $\Delta$  need to find a good domain!).  $\square$



Theorem. (first variation formula). Let  $(M, g)$  be a Riem. mfd, let  $\gamma: [a, b] \rightarrow M$  be a unit speed ps regular curve, let  $G: (-\varepsilon, \varepsilon) \times [a, b] \rightarrow M$  be a proper variation of  $\gamma$ , and let  $V$  be the variation field of  $G$ . Let  $a = a_0 < \dots < a_k = b$  be a partition of  $[a, b]$  s.t. each  $V|_{[a_{j-1}, a_j]}$  is smooth. Then

$$\frac{\partial}{\partial s} \Big|_{s=0} L_g(G(s, \cdot)) = - \int_a^b \langle V(t), D_\gamma \dot{\gamma}(t) \rangle dt$$

$$- \sum_{j=1}^{k-1} \langle V(a_j), \Delta_j \dot{\gamma} \rangle_g$$



Proof. Main input:

- compatibility of the connection with cov. derivatives
- symmetry lemma
- elementary analysis.

read notes  $\rightarrow \square$